



ZERTIFIKATSKURS

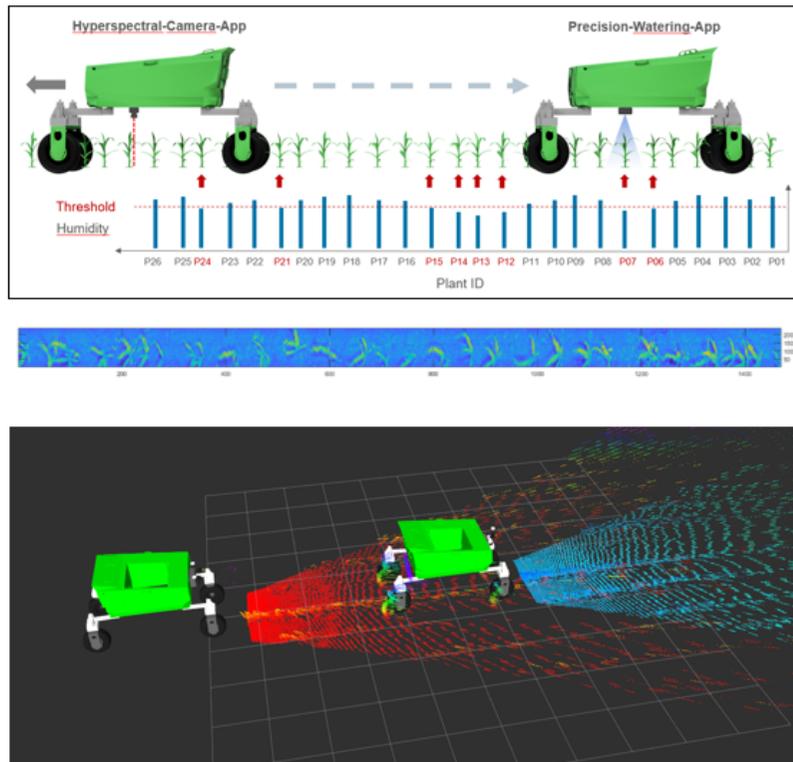
BILDGEBENDE SYSTEME IN DER AGRAR- UND LEBENSMITTELTECHNIK

Imaging in der Phänotypisierung

Arno Ruckelshausen



Landtechnik – Feldrobotik - Phänotypisierung



Quelle: Jan Roters, Masterarbeit, HS Osnabrück, 2018

IMAGING IN DER PHÄNOTYPIERUNG



UNIVERSITÄT HOHENHEIM

HOCHSCHULE OSNABRÜCK
UNIVERSITY OF APPLIED SCIENCES

GFPi

GFNR
Fachagentur Transferpartnerschaften RapsWelle e.V.

JKU JOZSEF ATTILA
UNIVERSITÄT SZEGED

PZO PFLANZENZUCHT OBERLIMPURG

SAATEN UNION
Züchtung der Zukunft

HYBRID
UNIVERSITÄT WÜRZBURG

DSV
UNIVERSITÄT BONN

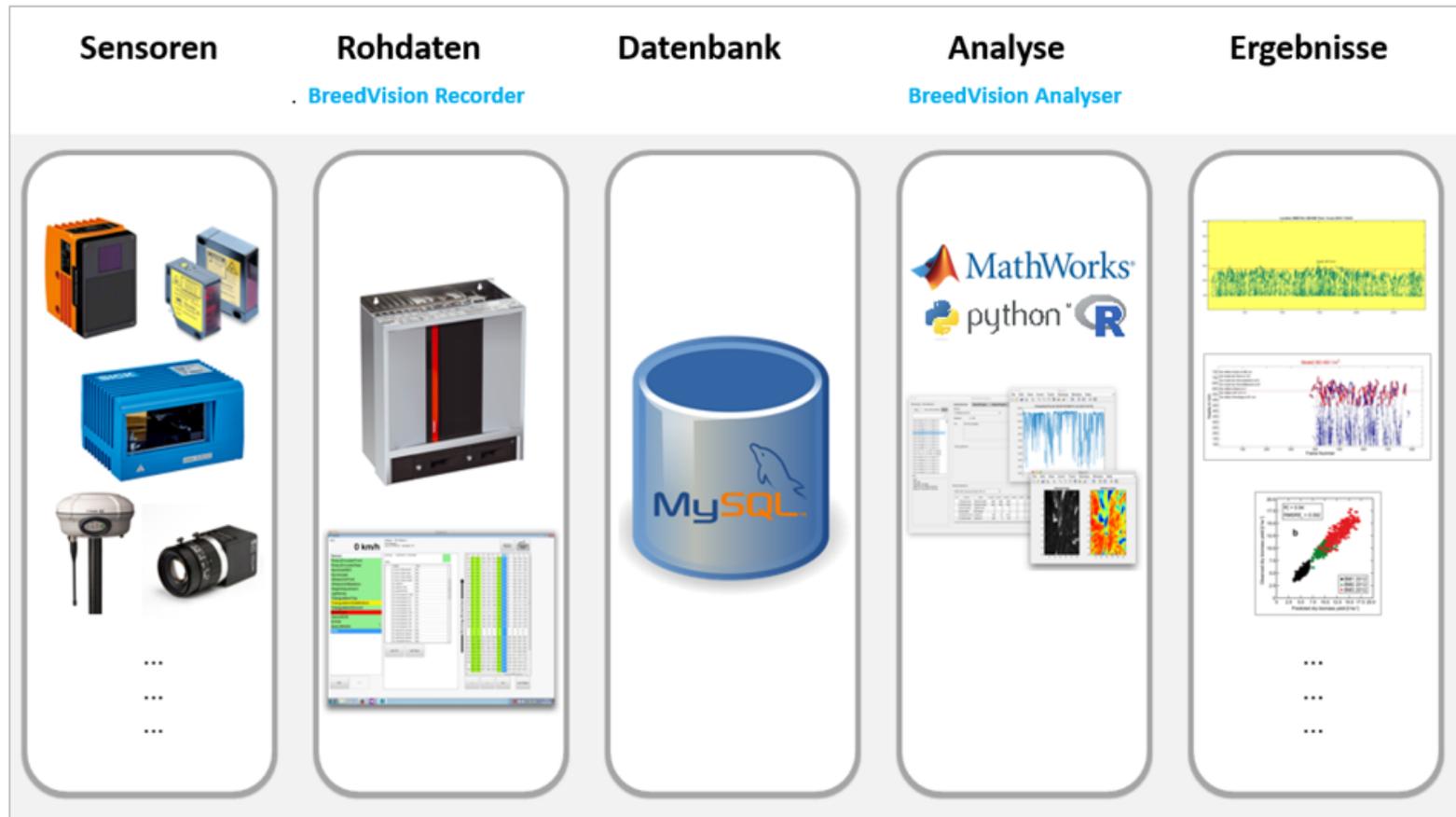
JKI
Julius Kühn-Institut

geo-konzept
inventarisieren, kartieren, optimieren.

BreedVision

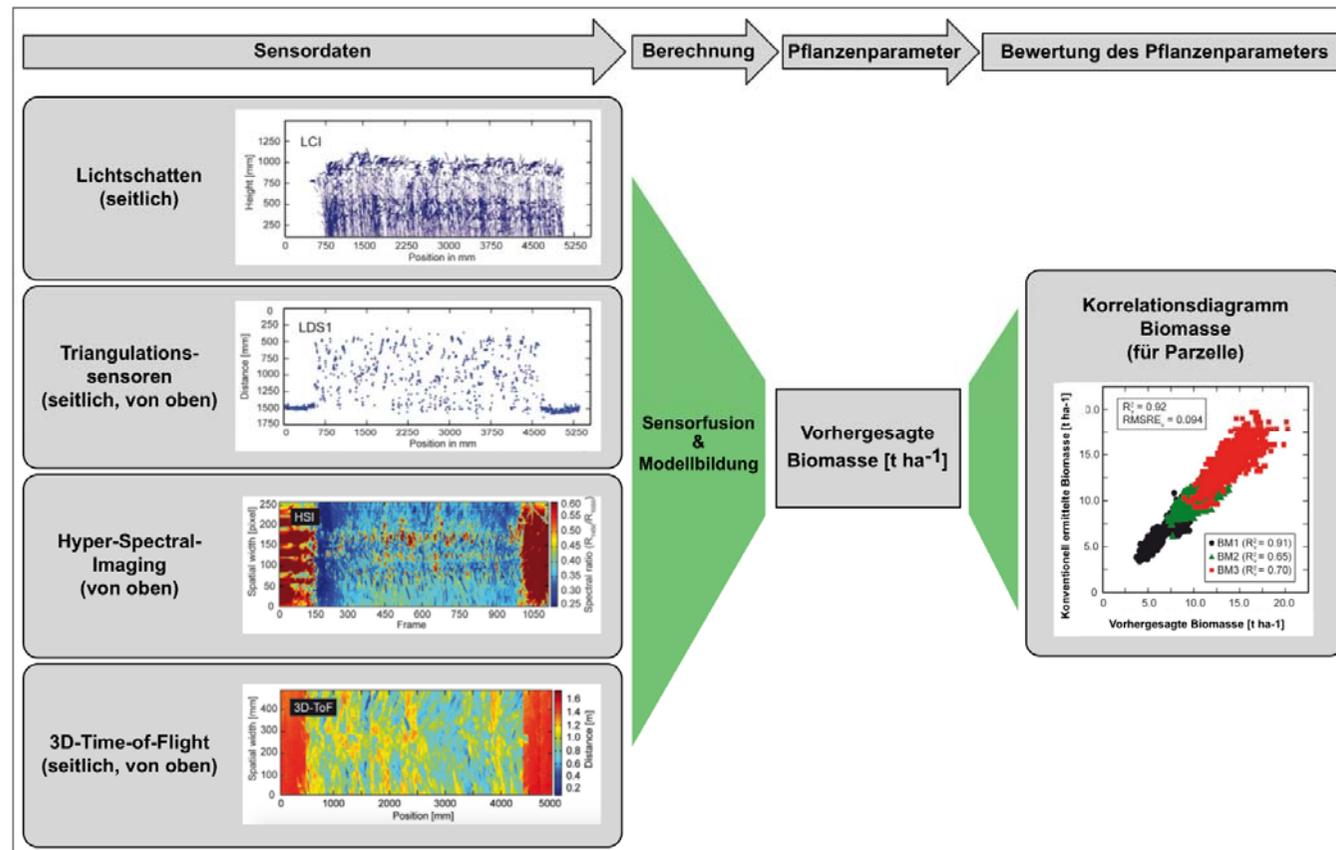
Kernbausteine: Konzept BreedVision

BreedVision



Quelle: Forschungsprojekte BreedVision, predbreed, SENSELGO

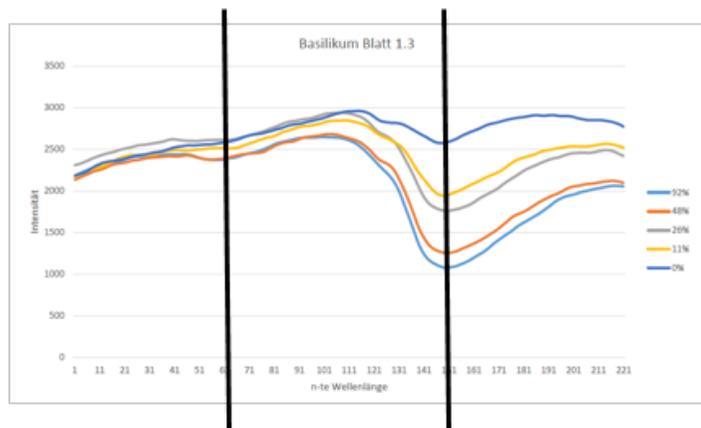
Beispiel: Feldbasierte Biomassebestimmung (Sensorfusion)



Quelle: Forschungsprojekt SENSELGO

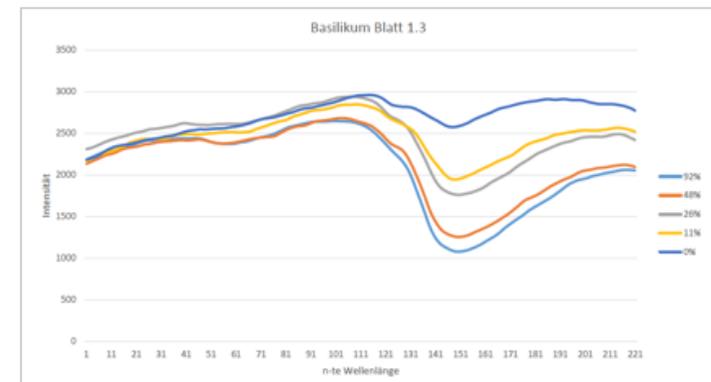
Dateninterpretation (Feuchtbestimmung von Pflanzen)

„Klassische“ Bild/Daten-Verarbeitung



- + Verständnis (Algorithmen)
- Entwicklungsaufwand
- Vielfalt

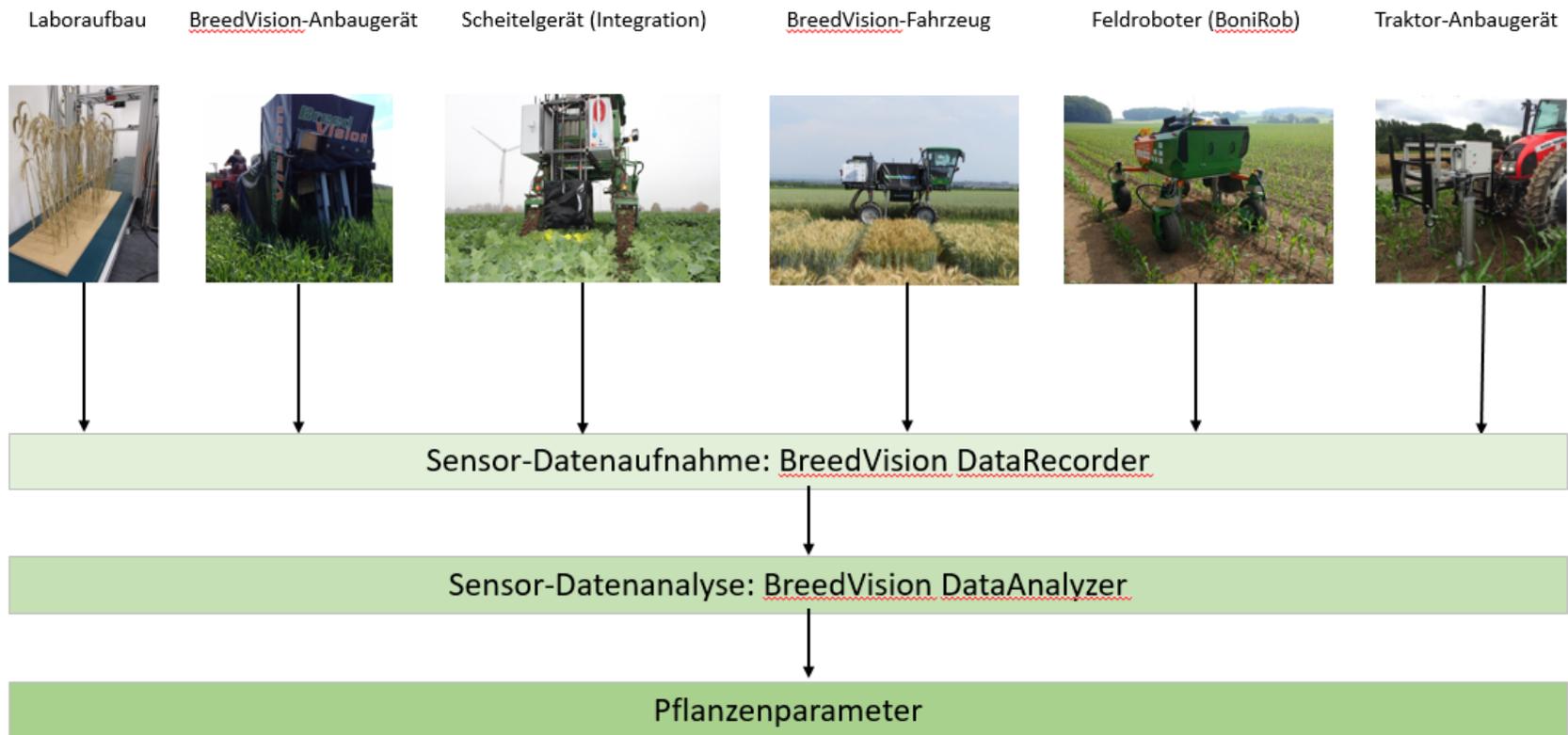
Neuronale Netze („Machine Learning“)



- Verständnis (Algorithmen)
- Labelling
- + Vielfalt

Quelle: Brümmer, Falz, Klodt, Peuker; Hausarbeit
„Sensorsysteme, HS Osnabrück, 2019

BreedVision-Konzept@Plattformen



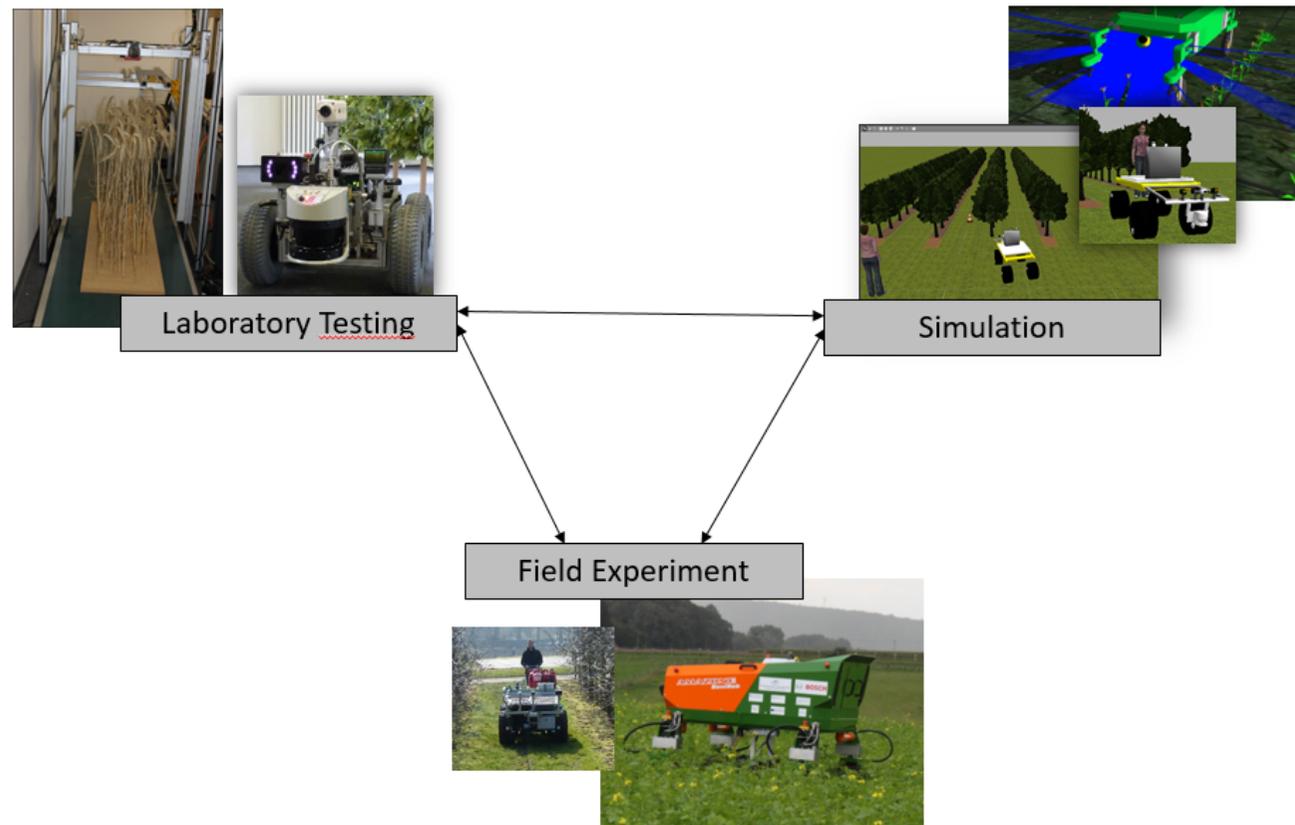
Quelle: Hochschule Osnabrück

BreedVision-Konzept@Plattformen



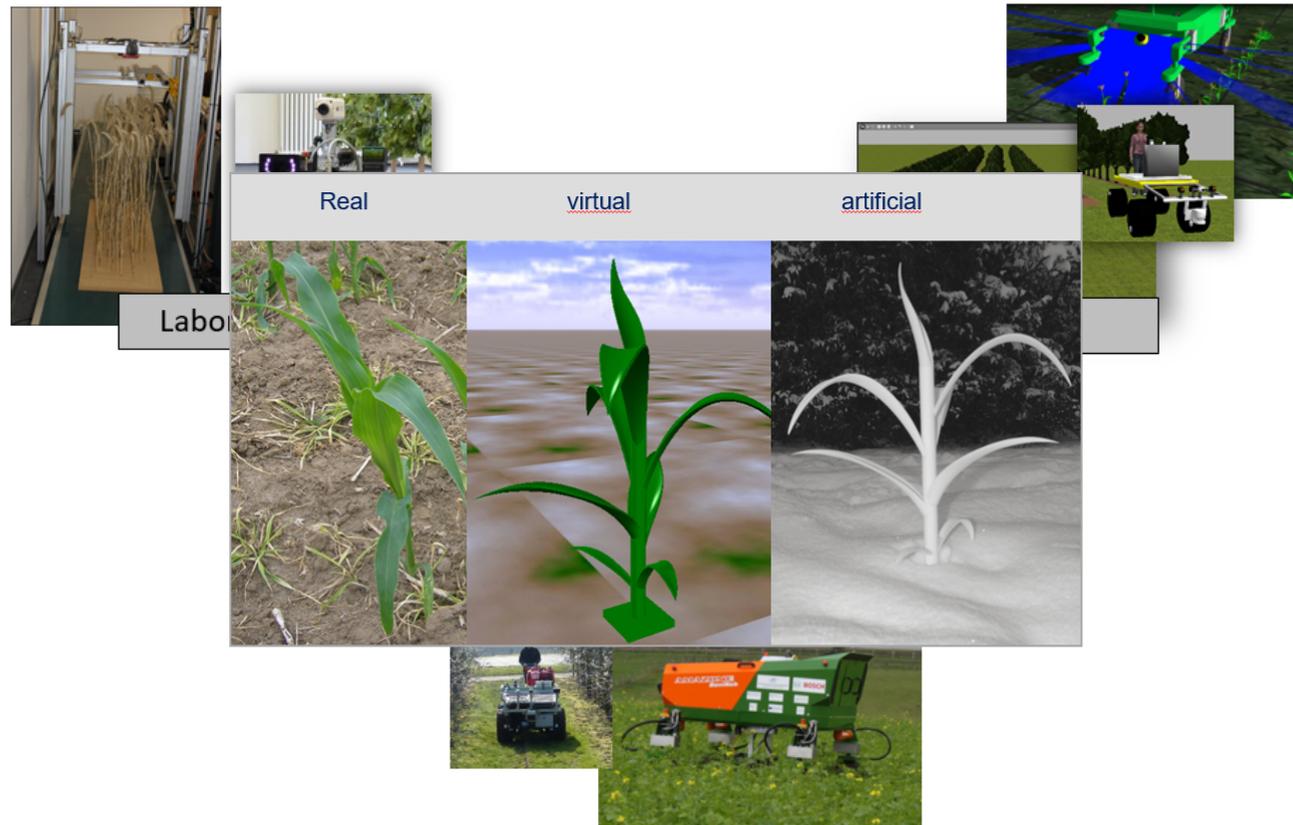
Quelle: Hochschule Osnabrück

Nature in the loop: Simulation – Teststände - Feldversuch



Quelle: Hochschule Osnabrück

Nature in the loop: Simulation – Teststände - Feldversuch



Quelle: Hochschule Osnabrück

File Panels Help

Interact Move Camera Select Focus Camera Measure 2D Pose Estimate 2D Nav Goal Publish Point

Displays

- Global Options
 - Fixed Frame: map
 - Background Color: 48; 48; 48
 - Frame Rate: 30
- Global Status: Ok
 - Fixed Frame: OK
 - Grid:
 - PointCloud2:
 - Status: Ok
 - Topic: /mwlp/visualization/mw...
 - Selectable:
 - Style: Points
 - Size (Pixels): 2
 - Alpha: 1
 - Decay Time: 0
 - Position Transfo...: XYZ
 - Color Transformer: RGB8
 - Queue Size: 10
 - PolygonMesh:
 - Status: Ok
 - Topic: /mwlp/visualization/pol...
 - CloudNormals:
 - Topic: /mwlp_normals_estima...
 - Color: 200; 200; 200
 - Alpha: 1
 - History Length: 1
 - Show each n-th ...: 100
 - Normals scale: 0,01

Topic: sensor_msgs/PointCloud2 topic to subscribe to.

Add Remove Rename

Time

ROS Time: 1445263606.85 ROS Elapsed: 75.38 Wall Time: 1445590228.89 Wall Elapsed: 377.89

Reset

Experimental 30 fps

```

INFO [1445590228.126505789, 1445263605.289813990]: Received image chunk
INFO [1445590226.328515881, 1445263606.480290164]: Trying to filter ...
INFO [1445590227.179921880, 1445263606.450285280]: Publishing mwlp:image and cloud
INFO [1445590227.327182415, 1445263606.501276195]: Done in callback
INFO [1445590229.176962555, 1445263606.509503777]: Received image chunk
  
```

Visualization controller for: Expanded_MWLP_image

Channels

- IntensitySum_NIR
- Scatter20Section_NIR
- Scatter40Section_NIR
- Scatter60Section_NIR
- Scatter80Section_NIR
- Scatter40Sum_Green
- Scatter60Sum_Green
- Scatter80Sum_Green
- Scatter40Sum_Red
- Scatter60Sum_Red
- Scatter80Sum_Red
- Scatter40Sum_NIR
- Scatter60Sum_NIR
- Scatter80Sum_NIR

NormalizedDifferencedVeg

Send Config Reset

Save Remove Rename